Mingfeng Shang

Website Google Scholar LinkedIn 500 Pillsbury Dr. SE, Minneapolis, MN, 55455 +1 (312)292-8384 shang140@umn.edu

EDUCATION

University of Minnesota, Twin cities

Exp. May 2024

Ph.D., Civil Engineering, Transportation Engineering

Advisor: Raphael E. Stern

University of Illinois, Urbana-Champaign

Dec 2018

Master of Science, Civil Engineering, Transportation Engineering

Southwest Jiaotong University, Chengdu, China

Jun 2017

Bachelor of Engineering, Civil Engineering

JOURNAL PUBLICATIONS

- [J6] M. Shang, S. Wang, and R. Stern. Extending ramp metering control to mixed autonomy traffic flow with varying degrees of automation. *Transportation Research Part C: Emerging Technologies*, 151:104119, 2023. Online Access.
- [J5] S. Wang, M. Shang, M. Levin, and R. Stern. A general approach to smoothing nonlinear mixed traffic via control of autonomous vehicles. *Transportation Research Part C: Emerging Technologies*, 146:103967, 2023. Online Access.
- [J4] M. Shang, B. Rosenblad, and R. Stern. A novel asymmetric car following model for driver-assist enabled vehicle dynamics. *IEEE Transactions on Intelligent Transportation Systems*, 23(9):15696–15706, 2022. Online Access.
- [J3] H Jeon, RF Benekohal, B Garshasebi, and M. Shang. Comparison of an adaptive signal system to time based coordination plan along a signalized arterial. *Advances in Transportation Studies*, 56, 2022. Online Access.
- [J2] M. Shang and R. E Stern. Impacts of commercially available adaptive cruise control vehicles on highway stability and throughput. *Transportation Research Part C: emerging technologies*, 122:102897. Online Access.
- [J1] M. Levin, **M. Shang**, and R. Stern. Effects of short-term travel on covid-19 spread: A novel seir model and case study in minnesota. *Plos One*, 16(1):e0245919, 2021. Online Access.

JOURNAL PUBLICATIONS IN REVIEW

- [JR3] S. Wang, M. Shang, and R. Stern. Analytical characterization of cyberattacks on adaptive cruise control vehicles. *IEEE Transactions on Intelligent Transportation Systems*, Under Review, 2023
- [JR2] M. Shang, S. Wang, and R. Stern. Modeling adaptive cruise control vehicle dynamics: A two-condition continuous asymmetric car-following model. *IEEE Transactions on Intelligent Vehicles*, Under Review, 2023
- [JR1] T. Li, M. Shang, S. Wang, and R. Stern. Understanding and detecting malicious cyberattacks on adaptive cruise control vehicles: A machine learning approach. *IEEE Transactions on Intelligent Vehicles*, Under Review, 2023

CONFERENCE PROCEEDINGS AND TECHNICAL REPORTS

- [C12] A. Zare, M. Shang, D.. Kan, and R. Stern. Modeling car-following behavior of electric adaptive cruise control vehicles using experimental testbed data. In 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC). IEEE, 2023
- [C11] M. Shang, S. Wang, and R. Stern. Capacity implications of personalized adaptive cruise control. In 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC). IEEE, 2023
- [C10] T. Li, B. Rosenblad, S. Wang, M. Shang, and R. Stern. Exploring energy impacts of cyberattacks on adaptive cruise control vehicles. In 2023 IEEE Intelligent Vehicles Symposium (IV), pages 1–6. IEEE, 2023. Online Access.
- [C9] M. Shang and R. Stern. Impacts of mixed autonomy traffic flow with adaptive cruise control vehicles on fuel consumption and emissions. In 2023 8th International Conference on Models and Technologies for Intelligent Transportation Systems (MT-ITS), pages 1–6. IEEE, 2023. Online Access.
- [C8] M. Shang, S. Wang, and R. Stern. Modeling adaptive cruise control vehicles: A continuous asymmetric car-following perspective. In 2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC), pages 923–928. IEEE, 2022. Online Access.
- [C7] S. Wang, M. Shang, M. Levin, and R. Stern. Smoothing nonlinear mixed traffic with autonomous vehicles: Control design. In 2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC), pages 661–666. IEEE, 2022. Online Access.
- [C6] T. Li, M. Shang, S. Wang, and R. Stern. Detecting stealthy cyberattacks on automated vehicles via generative adversarial networks. In 2022 IEEE 25th International Conference on Intelligent Transportation Systems (ITSC), pages 3632–3637. IEEE, 2022. Online Access.
- [C5] D. Vrabac, M. Shang, B. Butler, J. Pham, R. Stern, and P. Paré. Capturing the effects of transportation on the spread of covid-19 with a multi-networked seir model. In 2021 American Control Conference (ACC), pages 3152–3157. IEEE, 2021. Online Access.
- [C4] M. Shang and R. Stern. A hybrid fundamental diagram for modeling mixed human and automated traffic flow. In 2021 7th International Conference on Models and Technologies for Intelligent Transportation Systems (MT-ITS), pages 1–6. IEEE, 2021. Online Access.
- [C3] M. Shang and R. Stern. Calibrating heterogeneous car-following models for human drivers in oscillatory traffic conditions. In 2020 Forum on Integrated and Sustainable Transportation Systems (FISTS), pages 101–106. IEEE, 2020. Online Access.
- [C2] M. Shang, F. Hauer, and R. Stern. Do cut-ins matter: Assessing the impact of lane changing and string stability on traffic flow. In 2020 IEEE 23rd International Conference on Intelligent Transportation Systems (ITSC), pages 1–6. IEEE, 2020. Online Access.
- [C1] R. Benekohal, B. Garshasebi, H. Jeon, and M. Shang. Evaluation of adaptive signal control technology-volume 3: Comparison of tbc 2017 and asct 2017. Technical report, Illinois Center for Transportation/Illinois Department of Transportation, 2019. Online Access.

PRESENTATIONS

1.

- Capacity implications of personalized adaptive cruise control
 2023 IEEE 26th International Conference on Intelligent Transportation Systems (ITSC), Bilbao,
 Spain, Sep. 24, 2023 Sep. 28, 2023.
- 3. Impacts of mixed autonomy traffic flow with adaptive cruise control vehicles on fuel consumption and emissions

- 2023 8th International Conference on Models and Technologies for Intelligent Transportation Systems (MT-ITS), Nice, France, Jun. 13, 2023 Jun. 16, 2023.
- ${\it 4. \ Modeling \ adaptive \ cruise \ control \ vehicle \ dynamics: \ A \ two-condition \ continuous \ asymmetric \ car-following \ model}$
 - Transportation Research Board 102nd Annual Meeting, Washington DC, Jan. 08, 2023.
- 5. Flash talk: modeling and control of mixed autonomy traffic flow
 The 2022 INFORMS Annual Meeting, Indianapolis, IN, Oct. 16 Oct. 19, 2022.
- 6. A modified traffic fundamental diagram for the mixed autonomy highway traffic flow Mid-Continent Transportation Research Symposium, Ames, IA, Sep. 14 Sep. 15, 2022.
- 7. Modeling and control of mixed autonomy traffic flow UCLA Mathematical Challenges and Opportunities for Autonomous Vehicles Reunion Conference, Los Angeles, CA, Jun. 5 - Jun. 10, 2022.
- 8. A novel asymmetric car following model for driver-assist enabled vehicle dynamics
 ASCE International Conference on Transportation & Development, Seattle, WA, Jun 2, 2022.
- 9. Fuel consumption and emissions of mixed autonomy traffic flow
 Center for Transportation Studies Transportation Research Conference, Minneapolis, MN, Nov 4,
 2021.
- 10. Evaluation of US air transportation network reliability during the COVID-19 pandemic Transportation Research Board 100th Annual Meeting, Washington DC, Jan 25, 2021.

AWARDS AND HONORS

- 2023-24 Doctoral Dissertation Fellowship, University of Minnesota, 2023
 - Awarded to the most accomplished Ph.D. candidates across the university
- Matthew J. Huber Award, Center for Transportation Studies, University of Minnesota, 2023
 - For excellence in Transportation Research and Education, one doctoral winner per year
- Hsiao Shaw-Lundquist Fellowship, China Center, University of Minnesota, 2022
- Outstanding Graduate Student (with highest honors), Southwest Jiaotong University, 2017

TEACHING EXPERIENCE

Department of Civil, Environmental, and Geo-Engineering, University of Minnesota

- Teaching Assistant CEGE 4211/5211: Traffic Engineering Responsibilities: Graded assignments and held weekly office hours. Enrollment: 15
- Teaching Assistant CEGE 4211/5211: Traffic Engineering Fall 2021 Responsibilities: Graded assignments and held weekly office hours. Enrollment: 27

Spring 2020

• Lab Instructor CEGE 3201: Transportation Engineering Spring 2023
Responsibilities: Ran weekly 1-hour discussion section, held weekly office hours.
Enrollment: 22

STUDENTS MENTORED

- 1. Benjamin Rosenblad, Undergraduate student in Civil Engineering, University of Minnesota, Research on a novel asymmetric car following model for driver-assist enabled vehicle dynamics, May 2021 Aug. 2021 & exploring the risks and opportunities for ramp metering control in mixed autonomy traffic: a case study in Minnesota, Jan. 2023 Aug. 2023
- 2. Hannah Delker, Undergraduate student in Civil Engineering, University of Minnesota, Research on Extending ramp metering control to mixed autonomy traffic flow with varying degrees of automation, Sep. 2021 - Dec. 2021
- 3. Kenny Tran, Undergraduate student in Computer science, University of Minnesota, Research on microscopic lane changing modeling and simulation, Jan. 2020 - Aug. 2020
- 4. Joseph Pham, Undergraduate student in Civil Engineering, University of Minnesota, Research on evaluation of US air transportation network reliability during the COVID-19 pandemic, Jan. 2020 Aug. 2020

REFEREE SERVICES

- Journals refereed: IEEE Transactions on Intelligent Vehicles, Transportmetrica A: Transport Science, Transportation Research Part C: Emerging Technologies, Transportation Research Record, Scientific Reports, Advances in Bridge Engineering
- Conferences refereed: IEEE Conference on Decision and Control, IEEE International Conference on Intelligent Transportation Systems, Transportation Research Board Annual Meeting

PROFESSIONAL MEMBERSHIP

- American Society of Civil Engineers (ASCE), Student Member
- Institute of Electrical and Electronics Engineers (IEEE), Student Member